MATRIX GROUPS

(MTH565)

Quiz 6

Thursday, 16th October 2025

Name:		•
Roll Number:		
Obtained Marks:	/10	

EXAMINATION INSTRUCTIONS

- **1.** This is an **Open Book Examination**.
- 2. You can discuss with your friends but make sure write your own script. Answer all questions.
- 3. Show all necessary working steps clearly and legibly.
- **4.** State any theorems or results used. Only results discussed in lectures may be used without proof.
- **5.** The total point for the problems is 12, but the maximum obtainable score is 10.
- **6. Duration:** 9 hours (12:00-9:00 PM).
- 7. I will assume your honesty that you will stop at 9:00 PM and keep your answer script with you until I take it.

Good Luck!

Problem Set

The set of problems will describe an isomorphism between the quotient $SU(2)/\{\pm I\} \cong SO(3)$ which was a problem in the Homework 5 (Problem 2 (iii)).

→ Problem 1 –

The *n*-sphere is defined as

$$\mathbb{S}^n := \left\{ (x_1, \dots, x_{n+1}) \in \mathbb{R}^{n+1} : \sum_{i=1}^{n+1} x_i^2 = 1 \right\}.$$

Show that S^3 is a subgroup of the multiplicative group of quaternions $\mathbb{H}^{\times} = \mathbb{H} \setminus \{0\}$.

1.5

→ Problem 2 —

Prove that $SU(2) \cong S^3$ as a group.

1.5

-- Problem 3

Let Im $\mathbb{H} = \{x\mathbf{i} + y\mathbf{j} + z\mathbf{k} : x, y, z \in \mathbb{R}\}$ be the set of pure quaternions, which we identify with \mathbb{R}^3 . For $q \in S^3$ and $v \in \mathbb{Im} \mathbb{H}$, define

$$T_q: \operatorname{Im} \mathbb{H} \to \operatorname{Im} \mathbb{H}, \quad T_q(v) = qvq^{-1}.$$

- (i) Show that $T_q(v)$ is again a pure quaternion, that is, the map is well-defined.
- (ii) Prove that T_q is \mathbb{R} -linear.
- (iii) Show that $T_q \in SO(3)$.

1 + 1 + 1 = 3

→ Problem 4 –

With respect to the basis $\{e_1 = \mathbf{i}, e_2 = \mathbf{j}, e_3 = \mathbf{k}\}$, find out the matrix of T_q , and hence get a homomorphism

$$\psi: S^3 \to SO(3), \quad q \mapsto [T_q].$$

- (i) Show that the ker $\psi=\{\pm 1\}$. (By $\pm 1=(\pm 1,0,0,0)$).
- (ii) Also, show that ψ is surjective onto SO(3). (Hint: any rotation in \mathbb{R}^3 is rotation about some axis by some angle).
- (iii) Conclude that $S^3/\{\pm 1\} \cong SO(3)$ and hence conclude that $SU(2)/\pm I \cong SO(3)$.

1.5 + 3 + 1.5 = 6