

Morse-Bott functions, Cut locus and their relations

DMV-ÖMV Jahrestagung 2021

Sachchidanand Prasad

Indian Institute of Science Education and Research Kolkata

1st October, 2021



Young Topologists and Geometers

Outline of the talk

- 1 Geometric aspects of the cut locus
- 2 Topological aspects of the cut locus

Geometric aspects of the cut locus

Morse-Bott Function

Morse-Bott Function

Definition (Morse-Bott functions)

Morse-Bott Function

Definition (Morse-Bott functions)

Let M be a Riemannian manifold. A smooth submanifold $N \subset M$ is said to be *non-degenerate critical submanifold* of $f : M \rightarrow \mathbb{R}$ if $N \subseteq \text{Cr}(f)$

Morse-Bott Function

Definition (Morse-Bott functions)

Let M be a Riemannian manifold. A smooth submanifold $N \subset M$ is said to be *non-degenerate critical submanifold* of $f : M \rightarrow \mathbb{R}$ if $N \subseteq \text{Cr}(f)$ and for any $p \in N$, $\text{Hess}_p(f)$ is non-degenerate in the direction normal to N at p .

Morse-Bott Function

Definition (Morse-Bott functions)

Let M be a Riemannian manifold. A smooth submanifold $N \subset M$ is said to be *non-degenerate critical submanifold* of $f : M \rightarrow \mathbb{R}$ if $N \subseteq \text{Cr}(f)$ and for any $p \in N$, $\text{Hess}_p(f)$ is **non-degenerate in the direction normal to N at p** .

The $\text{Hess}_p(f)$ is **non-degenerate in the direction normal to N at p** means for any $V \in (T_p N)^\perp$ there exists $W \in (T_p N)^\perp$ such that $\text{Hess}_p(f)(V, W) \neq 0$.

Morse-Bott Function

Definition (Morse-Bott functions)

Let M be a Riemannian manifold. A smooth submanifold $N \subset M$ is said to be *non-degenerate critical submanifold* of $f : M \rightarrow \mathbb{R}$ if $N \subseteq \text{Cr}(f)$ and for any $p \in N$, $\text{Hess}_p(f)$ is non-degenerate in the direction normal to N at p . The function f is said to be *Morse-Bott* if the connected components of $\text{Cr}(f)$ are non-degenerate critical submanifolds.

The $\text{Hess}_p(f)$ is non-degenerate in the direction normal to N at p means for any $V \in (T_p N)^\perp$ there exists $W \in (T_p N)^\perp$ such that $\text{Hess}_p(f)(V, W) \neq 0$.

Cut locus of a submanifold

Cut locus of a submanifold

Definition (Distance minimal geodesic)

Cut locus of a submanifold

Definition (Distance minimal geodesic)

A geodesic γ is called a *distance minimal geodesic* joining N to p

Cut locus of a submanifold

Definition (Distance minimal geodesic)

A geodesic γ is called a *distance minimal geodesic* joining N to p if there exists $q \in N$

Cut locus of a submanifold

Definition (Distance minimal geodesic)

A geodesic γ is called a *distance minimal geodesic* joining N to p if there exists $q \in N$ such that γ is a minimal geodesic joining q to p

Cut locus of a submanifold

Definition (Distance minimal geodesic)

A geodesic γ is called a *distance minimal geodesic* joining N to p if there exists $q \in N$ such that γ is a minimal geodesic joining q to p and $l(\gamma) = d(p, N)$.

Cut locus of a submanifold

Definition (Distance minimal geodesic)

A geodesic γ is called a *distance minimal geodesic* joining N to p if there exists $q \in N$ such that γ is a minimal geodesic joining q to p and $l(\gamma) = d(p, N)$. We will call such geodesics as *N -geodesics*.

Cut locus of a submanifold

Definition (Distance minimal geodesic)

A geodesic γ is called a *distance minimal geodesic* joining N to p if there exists $q \in N$ such that γ is a minimal geodesic joining q to p and $l(\gamma) = d(p, N)$. We will call such geodesics as *N -geodesics*.

Definition (Cut locus)

Cut locus of a submanifold

Definition (Distance minimal geodesic)

A geodesic γ is called a *distance minimal geodesic* joining N to p if there exists $q \in N$ such that γ is a minimal geodesic joining q to p and $l(\gamma) = d(p, N)$. We will call such geodesics as *N -geodesics*.

Definition (Cut locus)

Let M be a Riemannian manifold

Cut locus of a submanifold

Definition (Distance minimal geodesic)

A geodesic γ is called a *distance minimal geodesic* joining N to p if there exists $q \in N$ such that γ is a minimal geodesic joining q to p and $l(\gamma) = d(p, N)$. We will call such geodesics as *N -geodesics*.

Definition (Cut locus)

Let M be a Riemannian manifold and N be any non-empty subset of M .

Cut locus of a submanifold

Definition (Distance minimal geodesic)

A geodesic γ is called a *distance minimal geodesic* joining N to p if there exists $q \in N$ such that γ is a minimal geodesic joining q to p and $l(\gamma) = d(p, N)$. We will call such geodesics as *N -geodesics*.

Definition (Cut locus)

Let M be a Riemannian manifold and N be any non-empty subset of M . If $\text{Cu}(N)$ denotes the *cut locus of N* ,

Cut locus of a submanifold

Definition (Distance minimal geodesic)

A geodesic γ is called a *distance minimal geodesic* joining N to p if there exists $q \in N$ such that γ is a minimal geodesic joining q to p and $l(\gamma) = d(p, N)$. We will call such geodesics as *N -geodesics*.

Definition (Cut locus)

Let M be a Riemannian manifold and N be any non-empty subset of M . If $\text{Cu}(N)$ denotes the *cut locus of N* , then we say that $q \in \text{Cu}(N)$ if there exists an N -geodesic joining N to q

Cut locus of a submanifold

Definition (Distance minimal geodesic)

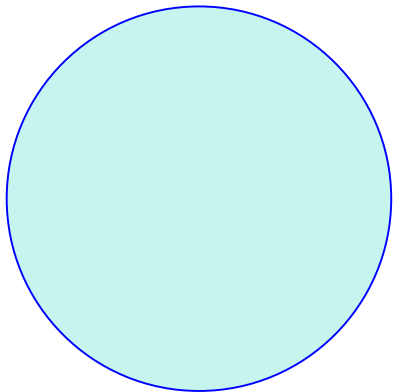
A geodesic γ is called a *distance minimal geodesic* joining N to p if there exists $q \in N$ such that γ is a minimal geodesic joining q to p and $l(\gamma) = d(p, N)$. We will call such geodesics as *N -geodesics*.

Definition (Cut locus)

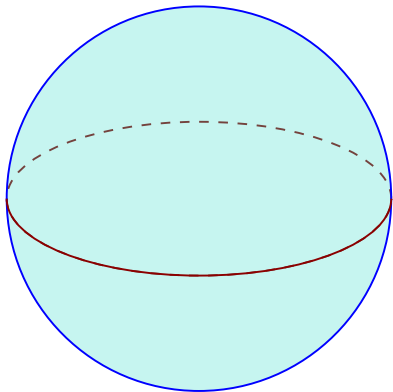
Let M be a Riemannian manifold and N be any non-empty subset of M . If $\text{Cu}(N)$ denotes the *cut locus of N* , then we say that $q \in \text{Cu}(N)$ if there exists an N -geodesic joining N to q such that any extension of it beyond q is not a distance minimal geodesic.

An Example

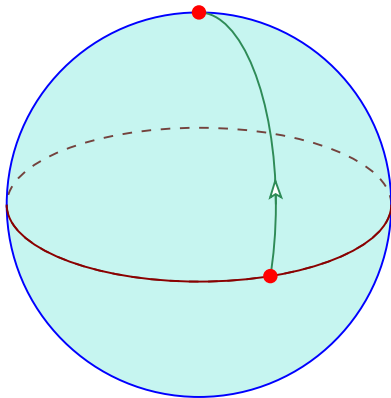
An Example



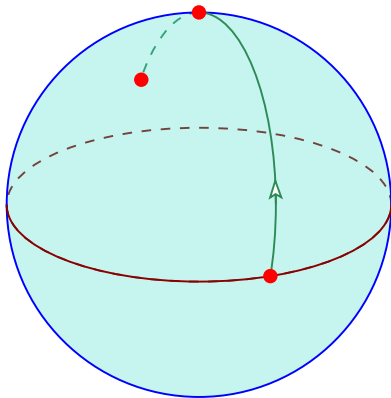
An Example



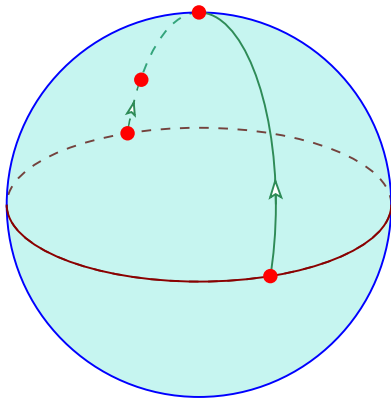
An Example



An Example



An Example



Separating set of N

Separating set of N

Definition (Separating set)

Separating set of N

Definition (Separating set)

Let N be a subset of a Riemannian manifold M .

Separating set of N

Definition (Separating set)

Let N be a subset of a Riemannian manifold M . The *separating set*, denoted by $\text{Se}(N)$,

Separating set of N

Definition (Separating set)

Let N be a subset of a Riemannian manifold M . The *separating set*, denoted by $\text{Se}(N)$, consists of all points $q \in M$

Separating set of N

Definition (Separating set)

Let N be a subset of a Riemannian manifold M . The *separating set*, denoted by $\text{Se}(N)$, consists of all points $q \in M$ such that at least two distance minimal geodesics from N to q exist.

Separating set of N

Definition (Separating set)

Let N be a subset of a Riemannian manifold M . The *separating set*, denoted by $\text{Se}(N)$, consists of all points $q \in M$ such that at least two distance minimal geodesics from N to q exist.

Theorem (Basu S., Prasad S., 2021)

For a complete Riemannian manifold M and a compact submanifold N of M ,

$$\overline{\text{Se}(N)} = \text{Cu}(N).$$

An illuminating example

An illuminating example

Let $M = M(n, \mathbb{R})$, the set of $n \times n$ matrices, and $N = O(n, \mathbb{R})$, set of all orthogonal $n \times n$ matrices.

An illuminating example

Let $M = M(n, \mathbb{R})$, the set of $n \times n$ matrices, and $N = O(n, \mathbb{R})$, set of all orthogonal $n \times n$ matrices. We fix the standard Euclidean metric on $M(n, \mathbb{R})$ by identifying it with \mathbb{R}^{n^2} .

An illuminating example

Let $M = M(n, \mathbb{R})$, the set of $n \times n$ matrices, and $N = O(n, \mathbb{R})$, set of all orthogonal $n \times n$ matrices. We fix the standard Euclidean metric on $M(n, \mathbb{R})$ by identifying it with \mathbb{R}^{n^2} . This induces a distance function given by

$$d(A, B) := \sqrt{\operatorname{tr}((A - B)^T(A - B))}, \quad A, B \in M(n, \mathbb{R})$$

An illuminating example

Let $M = M(n, \mathbb{R})$, the set of $n \times n$ matrices, and $N = O(n, \mathbb{R})$, set of all orthogonal $n \times n$ matrices. We fix the standard Euclidean metric on $M(n, \mathbb{R})$ by identifying it with \mathbb{R}^{n^2} . This induces a distance function given by

$$d(A, B) := \sqrt{\operatorname{tr}((A - B)^T(A - B))}, \quad A, B \in M(n, \mathbb{R})$$

Consider the distance squared function

$$f : M(n, \mathbb{R}) \rightarrow \mathbb{R}, \quad A \mapsto d^2(A, O(n, \mathbb{R})).$$

- The function is $f(A) = n + \text{tr}(A^T A) - 2\text{tr}(\sqrt{A^T A})$.
- It is differentiable at A if and only if A is invertible.
- It is a Morse-Bott function with critical submanifold as $O(n, \mathbb{R})$.
- If $\gamma(t)$ is an integral curve of $-\nabla f$ initialized at A , then

$$\frac{d\gamma}{dt} = -2\gamma(t) + 2(\gamma(t)^T)^{-1} \sqrt{\gamma(t)^T \gamma(t)}. \quad (1)$$

- The solution of (1) given by

$$\gamma(t) = Ae^{-2t} + (1 - e^{-2t})A(\sqrt{A^T A})^{-1}, \quad \gamma(0) = A. \quad (2)$$

- Note that $\gamma(t)$ is a flow line which deforms $GL(n, \mathbb{R})$ to $O(n, \mathbb{R})$.
- The separating set of $O(n, \mathbb{R})$ in $M(n, \mathbb{R})$ is set of singular matrices and as it is closed, the cut locus is the same.

- The function is $f(A) = n + \text{tr}(A^T A) - 2\text{tr}(\sqrt{A^T A})$.
- **It is differentiable at A if and only if A is invertible.**
- It is a Morse-Bott function with critical submanifold as $O(n, \mathbb{R})$.
- If $\gamma(t)$ is an integral curve of $-\nabla f$ initialized at A , then

$$\frac{d\gamma}{dt} = -2\gamma(t) + 2(\gamma(t)^T)^{-1} \sqrt{\gamma(t)^T \gamma(t)}. \quad (1)$$

- The solution of (1) given by

$$\gamma(t) = Ae^{-2t} + (1 - e^{-2t})A(\sqrt{A^T A})^{-1}, \quad \gamma(0) = A. \quad (2)$$

- Note that $\gamma(t)$ is a flow line which deforms $GL(n, \mathbb{R})$ to $O(n, \mathbb{R})$.
- The separating set of $O(n, \mathbb{R})$ in $M(n, \mathbb{R})$ is set of singular matrices and as it is closed, the cut locus is the same.

- The function is $f(A) = n + \text{tr}(A^T A) - 2\text{tr}(\sqrt{A^T A})$.
- It is differentiable at A if and only if A is invertible.
- **It is a Morse-Bott function with critical submanifold as $O(n, \mathbb{R})$.**
- If $\gamma(t)$ is an integral curve of $-\nabla f$ initialized at A , then

$$\frac{d\gamma}{dt} = -2\gamma(t) + 2\left(\gamma(t)^T\right)^{-1} \sqrt{\gamma(t)^T \gamma(t)}. \quad (1)$$

- The solution of (1) given by

$$\gamma(t) = Ae^{-2t} + (1 - e^{-2t})A\left(\sqrt{A^T A}\right)^{-1}, \quad \gamma(0) = A. \quad (2)$$

- Note that $\gamma(t)$ is a flow line which deforms $GL(n, \mathbb{R})$ to $O(n, \mathbb{R})$.
- The separating set of $O(n, \mathbb{R})$ in $M(n, \mathbb{R})$ is set of singular matrices and as it is closed, the cut locus is the same.

- The function is $f(A) = n + \text{tr}(A^T A) - 2\text{tr}(\sqrt{A^T A})$.
- It is differentiable at A if and only if A is invertible.
- It is a Morse-Bott function with critical submanifold as $O(n, \mathbb{R})$.
- If $\gamma(t)$ is an integral curve of $-\nabla f$ initialized at A , then

$$\frac{d\gamma}{dt} = -2\gamma(t) + 2\left(\gamma(t)^T\right)^{-1} \sqrt{\gamma(t)^T \gamma(t)}. \quad (1)$$

- The solution of (1) given by

$$\gamma(t) = Ae^{-2t} + (1 - e^{-2t})A\left(\sqrt{A^T A}\right)^{-1}, \quad \gamma(0) = A. \quad (2)$$

- Note that $\gamma(t)$ is a flow line which deforms $GL(n, \mathbb{R})$ to $O(n, \mathbb{R})$.
- The separating set of $O(n, \mathbb{R})$ in $M(n, \mathbb{R})$ is set of singular matrices and as it is closed, the cut locus is the same.

- The function is $f(A) = n + \text{tr}(A^T A) - 2\text{tr}(\sqrt{A^T A})$.
- It is differentiable at A if and only if A is invertible.
- It is a Morse-Bott function with critical submanifold as $O(n, \mathbb{R})$.
- If $\gamma(t)$ is an integral curve of $-\nabla f$ initialized at A , then

$$\frac{d\gamma}{dt} = -2\gamma(t) + 2(\gamma(t)^T)^{-1} \sqrt{\gamma(t)^T \gamma(t)}. \quad (1)$$

- The solution of (1) given by

$$\gamma(t) = Ae^{-2t} + (1 - e^{-2t})A(\sqrt{A^T A})^{-1}, \quad \gamma(0) = A. \quad (2)$$

- Note that $\gamma(t)$ is a flow line which deforms $GL(n, \mathbb{R})$ to $O(n, \mathbb{R})$.
- The separating set of $O(n, \mathbb{R})$ in $M(n, \mathbb{R})$ is set of singular matrices and as it is closed, the cut locus is the same.

- The function is $f(A) = n + \text{tr}(A^T A) - 2\text{tr}(\sqrt{A^T A})$.
- It is differentiable at A if and only if A is invertible.
- It is a Morse-Bott function with critical submanifold as $O(n, \mathbb{R})$.
- If $\gamma(t)$ is an integral curve of $-\nabla f$ initialized at A , then

$$\frac{d\gamma}{dt} = -2\gamma(t) + 2(\gamma(t)^T)^{-1} \sqrt{\gamma(t)^T \gamma(t)}. \quad (1)$$

- The solution of (1) given by

$$\gamma(t) = Ae^{-2t} + (1 - e^{-2t})A(\sqrt{A^T A})^{-1}, \quad \gamma(0) = A. \quad (2)$$

- **Note that $\gamma(t)$ is a flow line which deforms $GL(n, \mathbb{R})$ to $O(n, \mathbb{R})$.**
- The separating set of $O(n, \mathbb{R})$ in $M(n, \mathbb{R})$ is set of singular matrices and as it is closed, the cut locus is the same.

- The function is $f(A) = n + \text{tr}(A^T A) - 2\text{tr}(\sqrt{A^T A})$.
- It is differentiable at A if and only if A is invertible.
- It is a Morse-Bott function with critical submanifold as $O(n, \mathbb{R})$.
- If $\gamma(t)$ is an integral curve of $-\nabla f$ initialized at A , then

$$\frac{d\gamma}{dt} = -2\gamma(t) + 2(\gamma(t)^T)^{-1} \sqrt{\gamma(t)^T \gamma(t)}. \quad (1)$$

- The solution of (1) given by

$$\gamma(t) = Ae^{-2t} + (1 - e^{-2t})A(\sqrt{A^T A})^{-1}, \quad \gamma(0) = A. \quad (2)$$

- Note that $\gamma(t)$ is a flow line which deforms $GL(n, \mathbb{R})$ to $O(n, \mathbb{R})$.
- The separating set of $O(n, \mathbb{R})$ in $M(n, \mathbb{R})$ is set of singular matrices and as it is closed, the cut locus is the same.

Results generalized from the example

Theorem

Results generalized from the example

Theorem

Let M be a connected,

Results generalized from the example

Theorem

Let M be a connected, complete Riemannian manifold

Results generalized from the example

Theorem

Let M be a connected, complete Riemannian manifold and N be an embedded submanifold of M .

Results generalized from the example

Theorem

Let M be a connected, complete Riemannian manifold and N be an embedded submanifold of M . Suppose two N -geodesics exists joining N to $q \in M$

Results generalized from the example

Theorem

Let M be a connected, complete Riemannian manifold and N be an embedded submanifold of M . Suppose two N -geodesics exists joining N to $q \in M$. Then $d^2(N, \cdot) : M \rightarrow \mathbb{R}$ has no directional derivative at q .

Results generalized from the example

Theorem

Let M be a connected, complete Riemannian manifold and N be an embedded submanifold of M . Suppose two N -geodesics exists joining N to $q \in M$. Then $d^2(N, \cdot) : M \rightarrow \mathbb{R}$ has no directional derivative at q for vectors in direction of those two N -geodesic.

Results generalized from the example

Theorem

Let M be a connected, complete Riemannian manifold and N be an embedded submanifold of M . Suppose two N -geodesics exists joining N to $q \in M$. Then $d^2(N, \cdot) : M \rightarrow \mathbb{R}$ has no directional derivative at q for vectors in direction of those two N -geodesic.

Theorem

Let M be a complete Riemannian manifold

Results generalized from the example

Theorem

Let M be a connected, complete Riemannian manifold and N be an embedded submanifold of M . Suppose two N -geodesics exists joining N to $q \in M$. Then $d^2(N, \cdot) : M \rightarrow \mathbb{R}$ has no directional derivative at q for vectors in direction of those two N -geodesic.

Theorem

Let M be a complete Riemannian manifold and N be compact submanifold of M .

Results generalized from the example

Theorem

Let M be a connected, complete Riemannian manifold and N be an embedded submanifold of M . Suppose two N -geodesics exists joining N to $q \in M$. Then $d^2(N, \cdot) : M \rightarrow \mathbb{R}$ has no directional derivative at q for vectors in direction of those two N -geodesic.

Theorem

Let M be a complete Riemannian manifold and N be compact submanifold of M . Then N is a deformation retract of $M - \text{Cu}(N)$.

Results generalized from the example

Theorem

Let M be a connected, complete Riemannian manifold and N be an embedded submanifold of M . Suppose two N -geodesics exists joining N to $q \in M$. Then $d^2(N, \cdot) : M \rightarrow \mathbb{R}$ has no directional derivative at q for vectors in direction of those two N -geodesic.

Theorem

Let M be a complete Riemannian manifold and N be compact submanifold of M . Then N is a deformation retract of $M - \text{Cu}(N)$.

Theorem

The cut locus $\text{Cu}(N)$ is a strong deformation retract of $M - N$.

Results generalized from the example

Theorem

Let M be a connected, complete Riemannian manifold and N be an embedded submanifold of M . Suppose two N -geodesics exists joining N to $q \in M$. Then $d^2(N, \cdot) : M \rightarrow \mathbb{R}$ has no directional derivative at q for vectors in direction of those two N -geodesic.

Theorem

Let M be a complete Riemannian manifold and N be compact submanifold of M . Then N is a deformation retract of $M - \text{Cu}(N)$.

Theorem

The cut locus $\text{Cu}(N)$ is a strong deformation retract of $M - N$. In particular, $(M, \text{Cu}(N))$ is a good pair

Results generalized from the example

Theorem

Let M be a connected, complete Riemannian manifold and N be an embedded submanifold of M . Suppose two N -geodesics exists joining N to $q \in M$. Then $d^2(N, \cdot) : M \rightarrow \mathbb{R}$ has no directional derivative at q for vectors in direction of those two N -geodesic.

Theorem

Let M be a complete Riemannian manifold and N be compact submanifold of M . Then N is a deformation retract of $M - \text{Cu}(N)$.

Theorem

The cut locus $\text{Cu}(N)$ is a strong deformation retract of $M - N$. In particular, $(M, \text{Cu}(N))$ is a good pair and the number of path components of $\text{Cu}(N)$ equals that of $M - N$.

Outline of the proof of the deformation

Outline of the proof of the deformation

Define

$$\mathbf{s} : S(\nu) \rightarrow [0, \infty], \mathbf{s}(v) := \sup\{t \in [0, \infty) \mid \gamma_v|_{[0,t]} \text{ is an } N\text{-geodesic}\},$$

where $S(\nu)$ is the unit normal bundle of N and $[0, \infty]$ is the one-point compactification of $[0, \infty)$.

Outline of the proof of the deformation

Define

$$\mathbf{s} : S(\nu) \rightarrow [0, \infty], \mathbf{s}(v) := \sup\{t \in [0, \infty) \mid \gamma_v|_{[0,t]} \text{ is an } N\text{-geodesic}\},$$

where $S(\nu)$ is the unit normal bundle of N and $[0, \infty]$ is the one-point compactification of $[0, \infty)$. The map \mathbf{s} is continuous

Outline of the proof of the deformation

Define

$$\mathbf{s} : S(\nu) \rightarrow [0, \infty], \mathbf{s}(v) := \sup\{t \in [0, \infty) \mid \gamma_v|_{[0,t]} \text{ is an } N\text{-geodesic}\},$$

where $S(\nu)$ is the unit normal bundle of N and $[0, \infty]$ is the one-point compactification of $[0, \infty)$. The map \mathbf{s} is continuous and is finite if M is compact.

Outline of the proof of the deformation

Define

$$\mathbf{s} : S(\nu) \rightarrow [0, \infty], \mathbf{s}(v) := \sup\{t \in [0, \infty) \mid \gamma_v|_{[0,t]} \text{ is an } N\text{-geodesic}\},$$

where $S(\nu)$ is the unit normal bundle of N and $[0, \infty]$ is the one-point compactification of $[0, \infty)$. The map \mathbf{s} is continuous and is finite if M is compact. Note that the cut locus is

$$\text{Cu}(N) = \exp_\nu \{\mathbf{s}(v)v : v \in S(\nu)\},$$

Outline of the proof of the deformation

Define

$$\mathbf{s} : S(\nu) \rightarrow [0, \infty], \mathbf{s}(v) := \sup\{t \in [0, \infty) \mid \gamma_v|_{[0,t]} \text{ is an } N\text{-geodesic}\},$$

where $S(\nu)$ is the unit normal bundle of N and $[0, \infty]$ is the one-point compactification of $[0, \infty)$. The map \mathbf{s} is continuous and is finite if M is compact. Note that the cut locus is

$$\text{Cu}(N) = \exp_\nu \{\mathbf{s}(v)v : v \in S(\nu)\},$$

where $\exp_\nu : \nu \rightarrow M$, $\exp_\nu(p, v) := \exp_p(v)$.

Outline of the proof of the deformation

Define

$$\mathbf{s} : S(\nu) \rightarrow [0, \infty], \quad \mathbf{s}(v) := \sup\{t \in [0, \infty) \mid \gamma_v|_{[0,t]} \text{ is an } N\text{-geodesic}\},$$

where $S(\nu)$ is the unit normal bundle of N and $[0, \infty]$ is the one-point compactification of $[0, \infty)$. The map \mathbf{s} is continuous and is finite if M is compact. Note that the cut locus is

$$\text{Cu}(N) = \exp_\nu \{\mathbf{s}(v)v : v \in S(\nu)\},$$

where $\exp_\nu : \nu \rightarrow M$, $\exp_\nu(p, v) := \exp_p(v)$. Define an open neighborhood $U_0(N)$ of the zero section in the normal bundle as

$$U_0(N) := \{av : 0 \leq a < \mathbf{s}(v), v \in S(\nu)\}.$$

Outline of the proof of the deformation

Define

$$\mathbf{s} : S(\nu) \rightarrow [0, \infty], \mathbf{s}(v) := \sup\{t \in [0, \infty) \mid \gamma_v|_{[0,t]} \text{ is an } N\text{-geodesic}\},$$

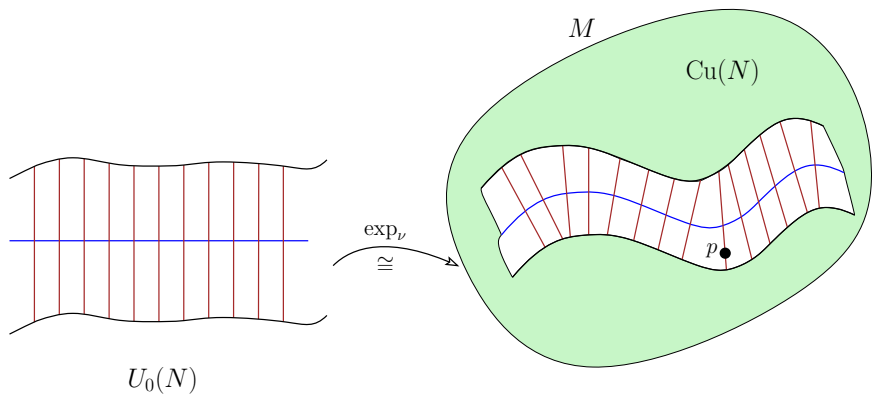
where $S(\nu)$ is the unit normal bundle of N and $[0, \infty]$ is the one-point compactification of $[0, \infty)$. The map \mathbf{s} is continuous and is finite if M is compact. Note that the cut locus is

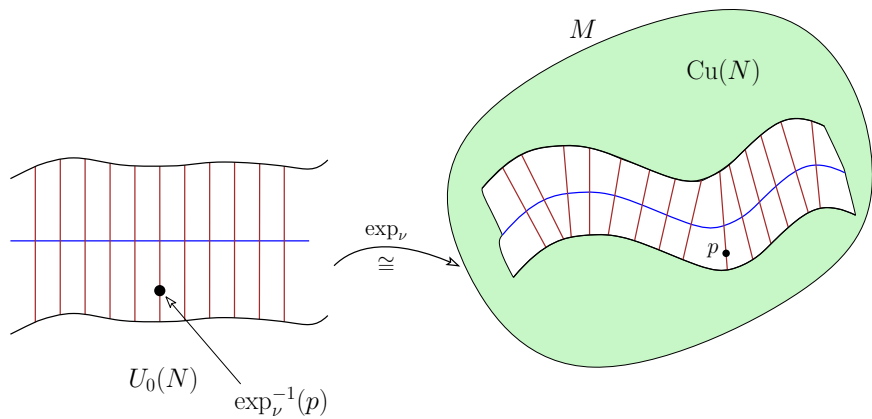
$$\text{Cu}(N) = \exp_\nu \{\mathbf{s}(v)v : v \in S(\nu)\},$$

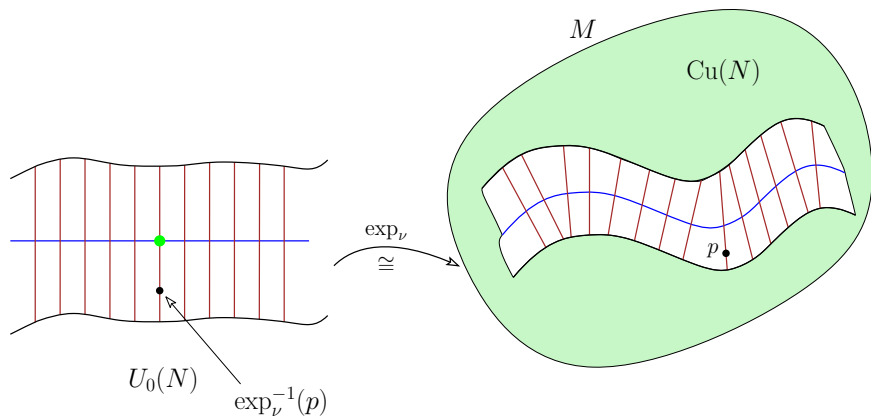
where $\exp_\nu : \nu \rightarrow M$, $\exp_\nu(p, v) := \exp_p(v)$. Define an open neighborhood $U_0(N)$ of the zero section in the normal bundle as

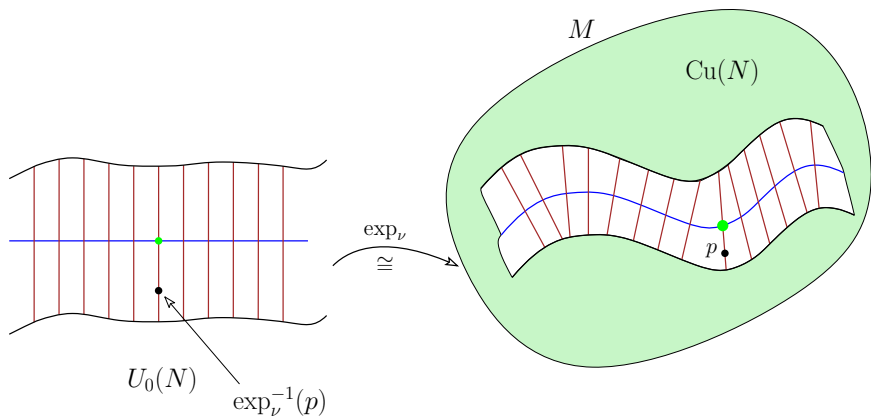
$$U_0(N) := \{av : 0 \leq a < \mathbf{s}(v), v \in S(\nu)\}.$$

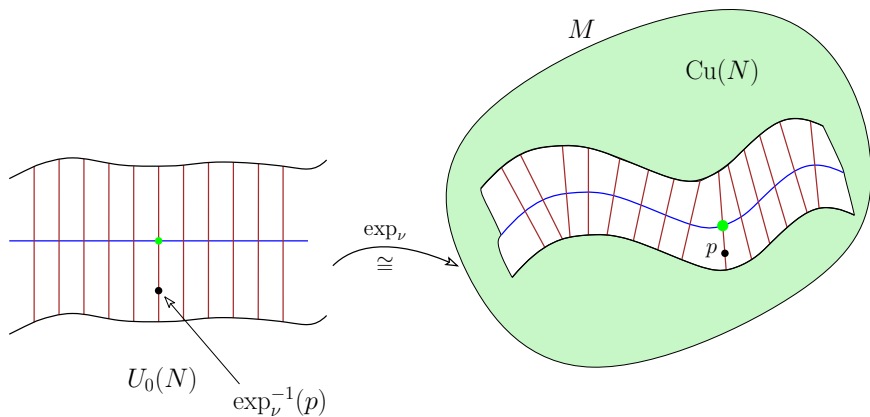
Note that \exp_ν is a diffeomorphism on $U_0(N)$ and set $U(N) = \exp_\nu(U_0(N)) = M - \text{Cu}(N)$.



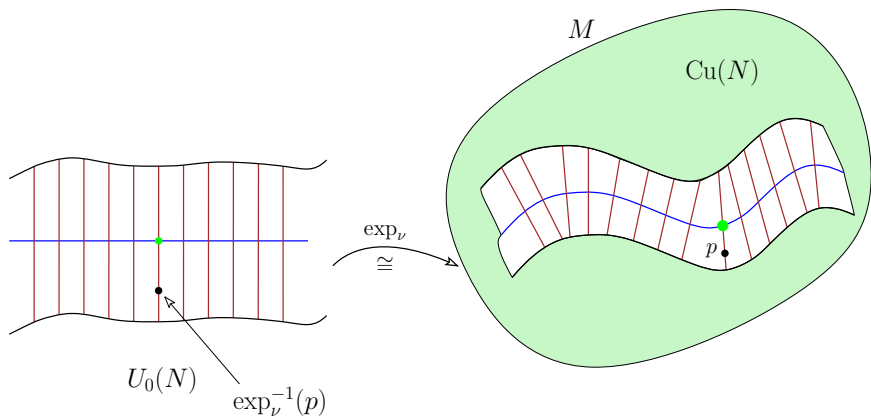








The space $U_0(N)$ deforms to the zero section on the normal bundle.



The space $U_0(N)$ deforms to the zero section on the normal bundle.

$$H : U_0(N) \times [0, 1] \rightarrow U_0(N), ((p, av), t) \mapsto (p, tav).$$

Now consider the following diagram:

$$\begin{array}{ccc}
 U_0(N) \times [0, 1] & \xrightarrow{H} & U_0(N) \\
 \exp_\nu^{-1} \uparrow & & \downarrow \exp_\nu \\
 U \times [0, 1] & \xrightarrow{F} & U \cong M - \text{Cu}(N)
 \end{array}$$

Now consider the following diagram:

$$\begin{array}{ccc}
 U_0(N) \times [0, 1] & \xrightarrow{H} & U_0(N) \\
 \exp_\nu^{-1} \uparrow & & \downarrow \exp_\nu \\
 U \times [0, 1] & \xrightarrow{F} & U \cong M - \text{Cu}(N)
 \end{array}$$

The map F can be defined by taking the compositions

$$F = \exp_\nu \circ H \circ \exp_\nu^{-1}.$$

Topological aspects of the cut locus

Thom space

Thom space

Definition (Thom space)

Let $\pi : E \rightarrow B$ be a real vector bundle over a paracompact space B with a metric. Let $D(E)$ be the unit disk bundle and $S(E)$ be the unit sphere bundle.

Thom space

Definition (Thom space)

Let $\pi : E \rightarrow B$ be a real vector bundle over a paracompact space B with a metric. Let $D(E)$ be the unit disk bundle and $S(E)$ be the unit sphere bundle. Then the *Thom space of E* , denote by $\text{Th}(E)$ is the quotient $\text{Th}(E) := D(E)/S(E)$.

Thom space

Definition (Thom space)

Let $\pi : E \rightarrow B$ be a real vector bundle over a paracompact space B with a metric. Let $D(E)$ be the unit disk bundle and $S(E)$ be the unit sphere bundle. Then the *Thom space of E* , denote by $\text{Th}(E)$ is the quotient $\text{Th}(E) := D(E)/S(E)$.

Remark

If B is compact, then $\text{Th}(E)$ is the one point compactification of E .

Definition (Rescaled exponential)

The *rescaled exponential* map is defined to be

$$\widetilde{\exp} : D(\nu) \rightarrow M, (p, v) \mapsto \begin{cases} \exp_p(\mathbf{s}(\hat{v})v), & \text{if } v = \|v\|\hat{v} \\ p, & \text{if } v = 0. \end{cases}$$

Definition (Rescaled exponential)

The *rescaled exponential* map is defined to be

$$\widetilde{\exp} : D(\nu) \rightarrow M, (p, v) \mapsto \begin{cases} \exp_p(\mathbf{s}(\hat{v})v), & \text{if } v = \|v\|\hat{v} \\ p, & \text{if } v = 0. \end{cases}$$

Remark

Since \mathbf{s} is continuous, the rescaled exponential is also continuous and is surjective.

Definition (Rescaled exponential)

The *rescaled exponential* map is defined to be

$$\widetilde{\text{exp}} : D(\nu) \rightarrow M, (p, v) \mapsto \begin{cases} \exp_p(\mathbf{s}(\hat{v})v), & \text{if } v = \|v\|\hat{v} \\ p, & \text{if } v = 0. \end{cases}$$

Remark

Since \mathbf{s} is continuous, the rescaled exponential is also continuous and is surjective. Also note that $\widetilde{\text{exp}}(S(\nu)) = \text{Cu}(N)$.

The Main Theorem

Theorem (Basu S., Prasad S., 2021)

Let N be an embedded submanifold inside a closed, connected Riemannian manifold M . If ν denotes the normal bundle of N in M , then there is a homeomorphism

$$\widetilde{\text{exp}} : D(\nu)/S(\nu) \xrightarrow{\cong} M/\text{Cu}(N).$$

Applications

Applications

- The inclusion map $i : \text{Cu}(N) \hookrightarrow M$ induces a long exact sequence in homology

Applications

- The inclusion map $i : \text{Cu}(N) \hookrightarrow M$ induces a long exact sequence in homology

$$\cdots \rightarrow H_j(\text{Cu}(N)) \xrightarrow{i_*} H_j(M) \rightarrow H_j(M, \text{Cu}(N)) \xrightarrow{\partial} H_{j-1}(\text{Cu}(N)) \rightarrow \cdots,$$

Applications

- The inclusion map $i : \text{Cu}(N) \hookrightarrow M$ induces a long exact sequence in homology

$$\cdots \rightarrow H_j(\text{Cu}(N)) \xrightarrow{i_*} H_j(M) \rightarrow H_j(M, \text{Cu}(N)) \xrightarrow{\partial} H_{j-1}(\text{Cu}(N)) \rightarrow \cdots,$$

so

$$\cdots \rightarrow H_j(\text{Cu}(N)) \xrightarrow{i_*} H_j(M) \xrightarrow{q} \tilde{H}_j(\text{Th}(\nu)) \xrightarrow{\partial} H_{j-1}(\text{Cu}(N)) \rightarrow \cdots$$

Applications

- The inclusion map $i : \text{Cu}(N) \hookrightarrow M$ induces a long exact sequence in homology

$$\cdots \rightarrow H_j(\text{Cu}(N)) \xrightarrow{i_*} H_j(M) \rightarrow H_j(M, \text{Cu}(N)) \xrightarrow{\partial} H_{j-1}(\text{Cu}(N)) \rightarrow \cdots,$$

so

$$\cdots \rightarrow H_j(\text{Cu}(N)) \xrightarrow{i_*} H_j(M) \xrightarrow{q} \tilde{H}_j(\text{Th}(\nu)) \xrightarrow{\partial} H_{j-1}(\text{Cu}(N)) \rightarrow \cdots$$

- If N is a closed submanifold of M with l components, and $\dim M = d$,

Applications

- The inclusion map $i : \text{Cu}(N) \hookrightarrow M$ induces a long exact sequence in homology

$$\cdots \rightarrow H_j(\text{Cu}(N)) \xrightarrow{i_*} H_j(M) \rightarrow H_j(M, \text{Cu}(N)) \xrightarrow{\partial} H_{j-1}(\text{Cu}(N)) \rightarrow \cdots,$$

so

$$\cdots \rightarrow H_j(\text{Cu}(N)) \xrightarrow{i_*} H_j(M) \xrightarrow{q} \tilde{H}_j(\text{Th}(\nu)) \xrightarrow{\partial} H_{j-1}(\text{Cu}(N)) \rightarrow \cdots$$

- If N is a closed submanifold of M with l components, and $\dim M = d$, then $H_{d-1}(\text{Cu}(N))$ is free abelian of rank $l - 1$ and $H_{d-j}(\text{Cu}(N)) \cong H^j(M)$ if $j - 2 \geq k$, where k is the maximum of the dimension of the components of N .

Applications

- The inclusion map $i : \text{Cu}(N) \hookrightarrow M$ induces a long exact sequence in homology

$$\cdots \rightarrow H_j(\text{Cu}(N)) \xrightarrow{i_*} H_j(M) \rightarrow H_j(M, \text{Cu}(N)) \xrightarrow{\partial} H_{j-1}(\text{Cu}(N)) \rightarrow \cdots,$$

so

$$\cdots \rightarrow H_j(\text{Cu}(N)) \xrightarrow{i_*} H_j(M) \xrightarrow{q} \tilde{H}_j(\text{Th}(\nu)) \xrightarrow{\partial} H_{j-1}(\text{Cu}(N)) \rightarrow \cdots$$

- If N is a closed submanifold of M with l components, and $\dim M = d$, then $H_{d-1}(\text{Cu}(N))$ is free abelian of rank $l - 1$ and $H_{d-j}(\text{Cu}(N)) \cong H^j(M)$ if $j - 2 \geq k$, where k is the maximum of the dimension of the components of N .
- Let N be a smooth homology k -sphere, $k > 0$, embedded in a smooth Riemannian manifold M homeomorphic to S^d .

Applications

- The inclusion map $i : \text{Cu}(N) \hookrightarrow M$ induces a long exact sequence in homology

$$\cdots \rightarrow H_j(\text{Cu}(N)) \xrightarrow{i_*} H_j(M) \rightarrow H_j(M, \text{Cu}(N)) \xrightarrow{\partial} H_{j-1}(\text{Cu}(N)) \rightarrow \cdots,$$

so

$$\cdots \rightarrow H_j(\text{Cu}(N)) \xrightarrow{i_*} H_j(M) \xrightarrow{q} \tilde{H}_j(\text{Th}(\nu)) \xrightarrow{\partial} H_{j-1}(\text{Cu}(N)) \rightarrow \cdots$$

- If N is a closed submanifold of M with l components, and $\dim M = d$, then $H_{d-1}(\text{Cu}(N))$ is free abelian of rank $l - 1$ and $H_{d-j}(\text{Cu}(N)) \cong H^j(M)$ if $j - 2 \geq k$, where k is the maximum of the dimension of the components of N .
- Let N be a smooth homology k -sphere, $k > 0$, embedded in a smooth Riemannian manifold M homeomorphic to S^d . If $d \geq k + 3$, then the cut locus $\text{Cu}(N)$ is homotopy equivalent to S^{d-k-1} .

- Let N be a real analytic homology k -sphere embedded in a real analytic homology d -sphere M . If $d \geq k + 3$, then the cut locus $\text{Cu}(N)$ is a simplicial complex of dimension at most $(d - 1)$, having the homology of $(d - k - 1)$ -sphere with fundamental group isomorphic to that of M .

Thank You for your attention!